SMOOTH ERGODIC THEORY AND NONUNIFORMLY HYPERBOLIC DYNAMICS

LUIS BARREIRA AND YAKOV PESIN

Contents

Introduction		1
1.	Lyapunov exponents of dynamical systems	3
2.	Examples of systems with nonzero exponents	6
3.	Lyapunov exponents associated with sequences of matrices	18
4.	Cocycles and Lyapunov exponents	24
5.	Regularity and Multiplicative Ergodic Theorem	31
6.	Cocycles over smooth dynamical systems	46
7.	Methods for estimating exponents	54
8.	Local manifold theory	62
9.	Global manifold theory	73
10.	Absolute continuity	79
11.	Smooth invariant measures	83
12.	Metric entropy	95
13.	Genericity of systems with nonzero exponents	102
14.	SRB-measures	112
15.	Hyperbolic measures I: topological properties	120
16.	Hyperbolic measures II: entropy and dimension	127
17.	Geodesic flows on manifolds without conjugate points	133
18.	Dynamical systems with singularities: the conservative case	138
19.	Hyperbolic attractors with singularities	142
Appendix A. Decay of correlations, by Omri Sarig		151
References		160
Index		170

INTRODUCTION

The goal of this chapter is to describe the contemporary status of nonuniform hyperbolicity theory. We present the core notions and results of the theory as well as discuss recent developments and some open problems. We also describe essentially all known examples of nonuniformly hyperbolic systems. Following the principles of the Handbook we include informal discussions of many results and sometimes outline their proofs.

Originated in the works of Lyapunov [170] and Perron [193, 194] the nonuniform hyperbolicity theory has emerged as an independent discipline in the works of Oseledets [191] and Pesin [197]. Since then it has become one of the major parts of